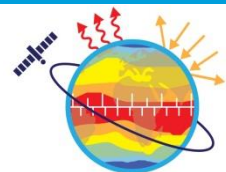
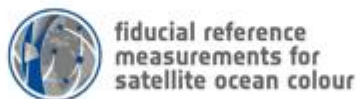


# The steps to an uncertainty budget

Emma Woolliams

4 April 2017

Prepared by Paul Miller



Metrology for Earth  
Observation and Climate

<http://www.emceoc.org>

**EMRP**

European Metrology Research Programme  
■ Programme of EURAMET

The EMRP is jointly funded by the EMRP participating countries  
within EURAMET and the European Union



# Uncertainty

- Where to start?
- What to do?
- How to be consistent?
- Make it easy.



# At the end of this module, you should understand

- Uncertainty analysis is a multi-step process

Understanding the problem

Determining the formal relationships

Propagating the uncertainties

- How to develop an uncertainty budget
  - 8 steps to an uncertainty budget

- There is no single right way
  - Mathematical / modelling
  - Experimental
  - Combination

# 8 steps to an uncertainty budget

- Understanding the problem
  - Step 1: Describing the Traceability Chain
  - Step 2: Writing down the calculation equations
  - Step 3: Considering the sources of uncertainty
- Determining the formal relationships
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# UNCERTAINTY ANALYSIS IS A MULTI-STEP PROCESS

# At the end of this module, you should understand

- Uncertainty analysis is a multi-step process

## **Understanding the problem**

Determining the formal relationships

Propagating the uncertainties

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- There is no single right way
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An unbroken chain



SI



# Describing the Traceability Chain

SI Units



**Cryogenic  
radiometer**



**Primary  
Standard**



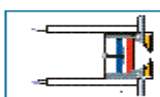
**Laser**



**Reference  
photodiode**

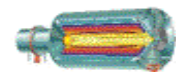


**Laser**



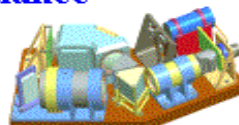
**Filter-  
radiometer**

**Radiance  
(T via Planck)**



**Blackbody  
3500 K**

**Spectrometer  
Radiance /  
Irradiance**



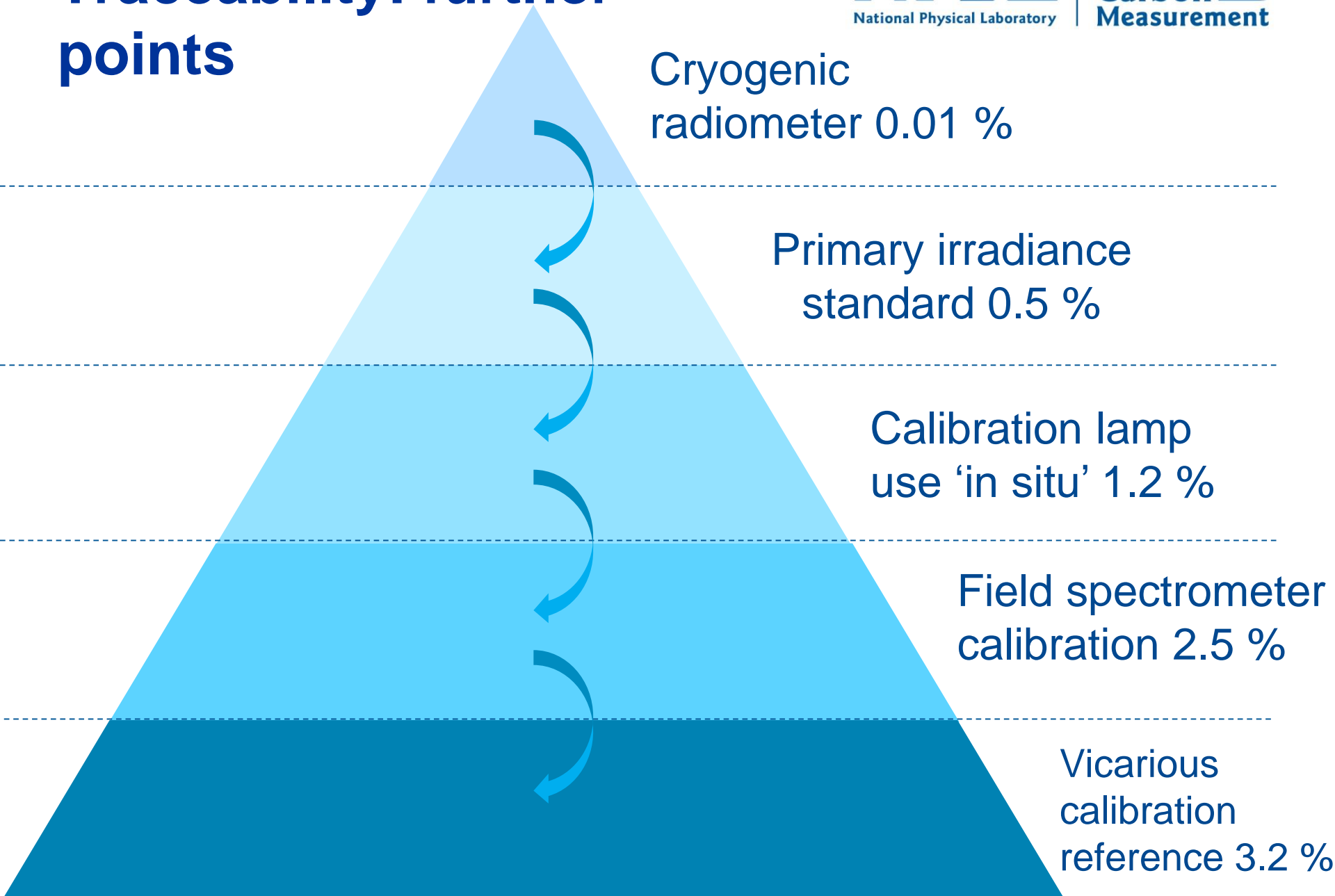
**Satellite  
Earth Imager**



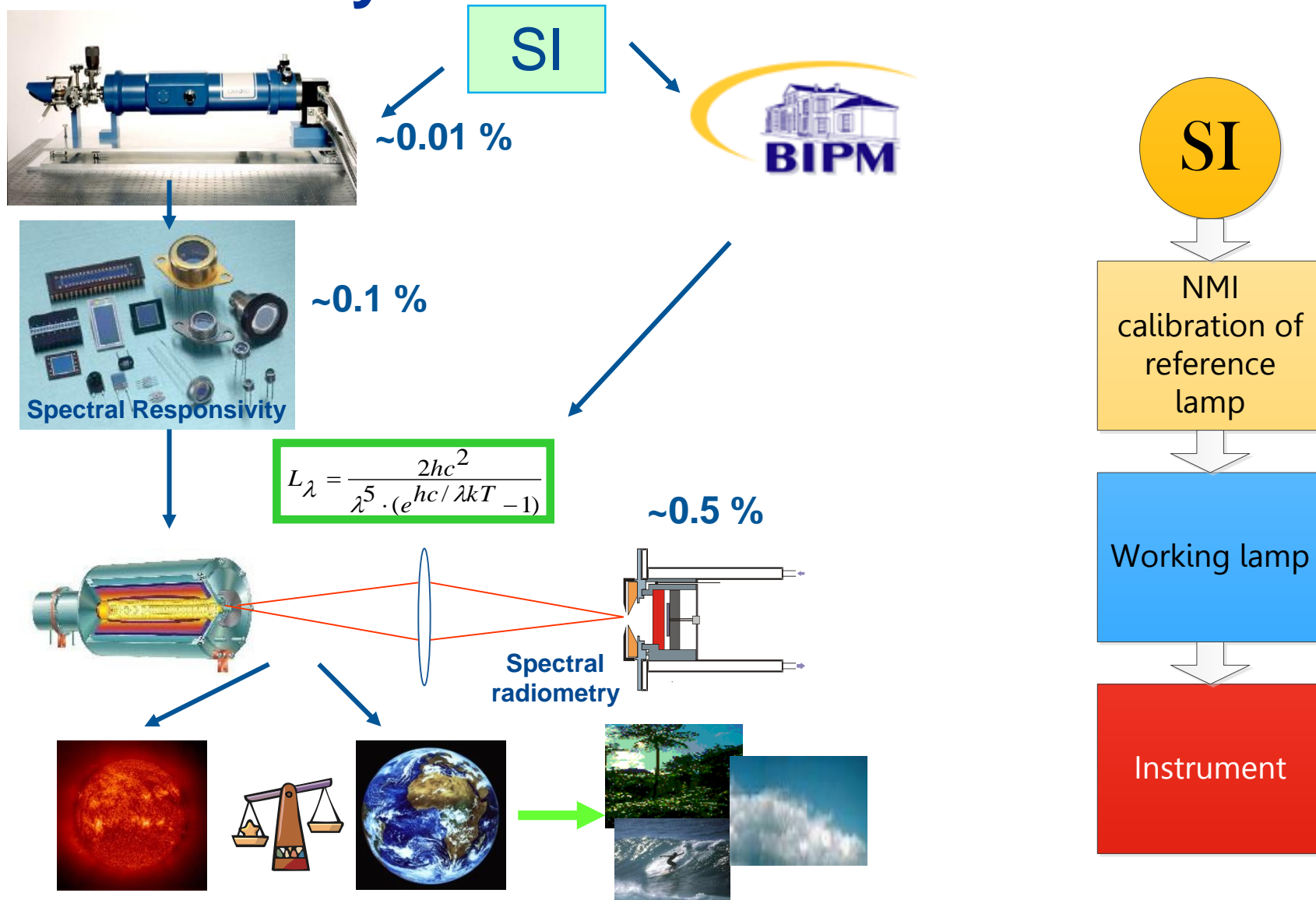
**Standard  
lamp**



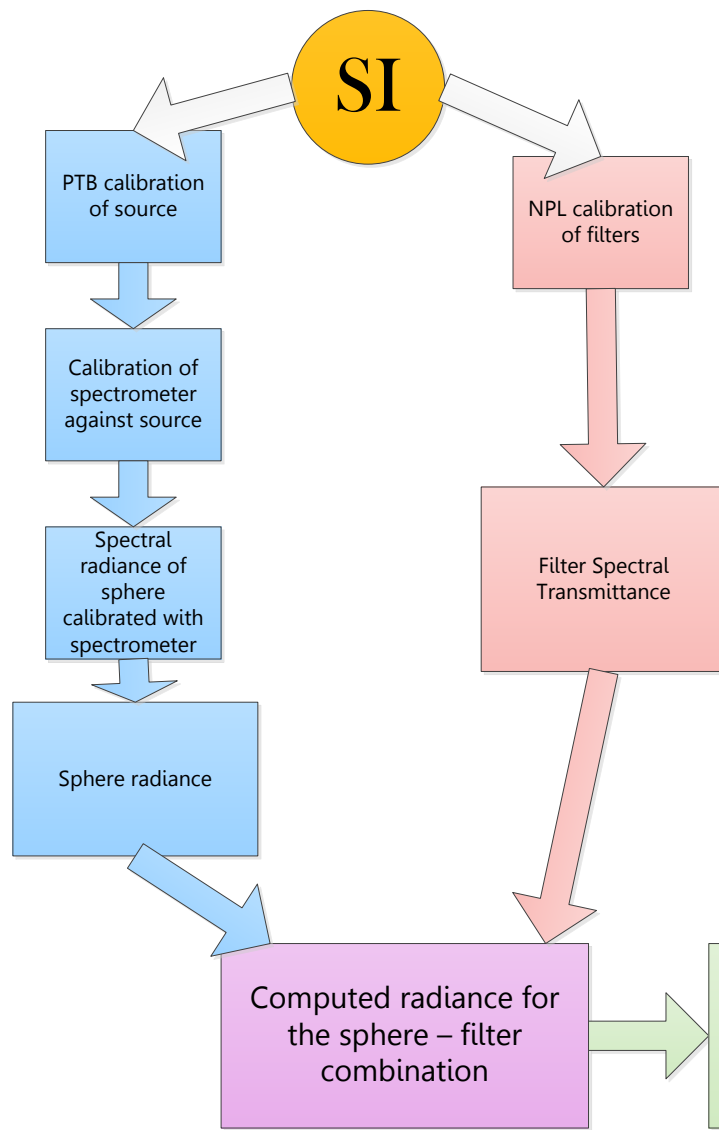
# Traceability: further points



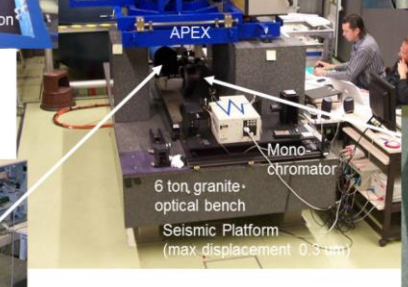
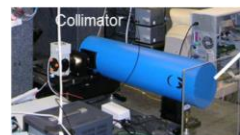
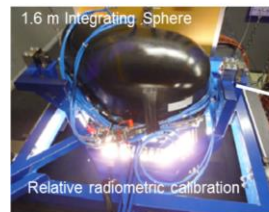
# Describing the Traceability Chain



# Describing the Traceability Chain



Calibration Home Base at DLR



# Understanding the problem

- Understanding the problem
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# Writing down the calculation equations



$$L_s = \frac{E_{\text{FEL}} \beta_{0-45}}{\pi}$$

# Understanding the problem

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# Considering the sources of uncertainty





# Considering the sources of uncertainty



## Lamp additional effects

- Ageing
- Alignment
- Current stability



## Distance accuracy



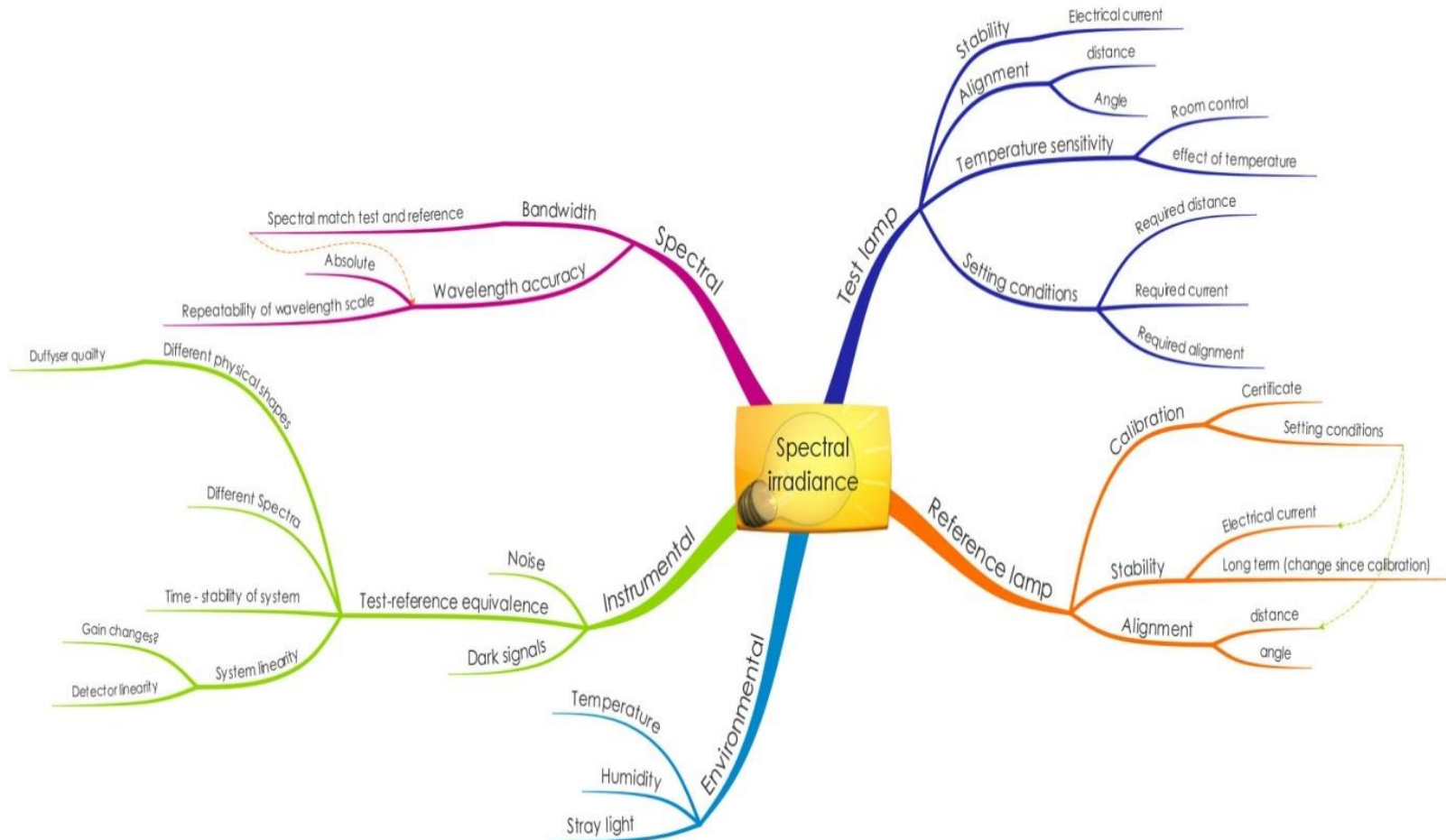
## Diffuser additional effects

- Ageing
- Uniformity



## Random noise

# Considering the sources of uncertainty



# Determining the formal relationships

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# Creating the measurement equation



$$L_s = \frac{E_{\text{FEL}} \beta_{0-45}}{\pi}$$

$$L_s = \frac{E_{\text{FEL}} \beta_{0-45}}{\pi} \frac{d_{\text{cal}}^2}{d_{\text{use}}^2} K_{\text{lamp\_stab}} K_{\text{align}} K_{\text{current}} K_{\text{diff\_stab}} K_{\text{unif}}$$

$$L_s = \frac{E_{\text{FEL}} \beta_{0-45}}{\pi} \frac{d_{\text{cal}}^2}{d_{\text{use}}^2}$$

# Determining the formal relationships

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# Determining the sensitivity coefficients

$$u_c^2(y) = \sum_{i=1}^n \left( \frac{\partial f}{\partial x_i} \right)^2 u^2(x_i) + 2 \sum_{i=1}^{n-1} \sum_{j=i+1}^n \frac{\partial f}{\partial x_i} \frac{\partial f}{\partial x_j} u(x_i, x_j)$$

- There is no single right way
  - **Mathematical / modelling**
  - **Experimental**
  - **Combination**

# Determining the sensitivity coefficients

- Do an experiment
- Analytical expression
- Model it



$$\begin{aligned}
 y'_u &= u^2 + 3\sqrt{u} - 1 \quad u = x^4 + 1 \quad y'_x = \dots \\
 &= (u^2 + 3\sqrt{u} - 1)'_u (x^4 + 1)'_x = (2u + \frac{3}{2\sqrt{u}}) * 4x \\
 &= (2(x^4 + 1) + \frac{3}{2\sqrt{x^4 + 1}}) * 4x \\
 \lim_{x \rightarrow \infty} (1 + \frac{2}{x})^{x+5} &= ((1 + \frac{2}{x})^{\frac{x}{2}})^2 * (1 + \frac{2}{x})^5 \quad \lim_{x \rightarrow \infty} \\
 e^{2*1} &= e^2 \quad \lim_{x \rightarrow a} \sqrt[p]{f(x)} = \sqrt[p]{\lim_{x \rightarrow a} f(x)} \\
 A \lim_{x \rightarrow a} b^{f(x)} &= b^A \quad b = \text{const}, \lim_{x \rightarrow a} f(x) = \\
 n \log_c f(x) &= \log_c [\lim_{x \rightarrow a} f(x)], \quad c = \text{const} \quad \lim_{x \rightarrow a}
 \end{aligned}$$



# Determining the formal relationships

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# Assigning uncertainties

Uncertainty component	Associated uncertainty		(relative)	Uncertainty associated with radiance due to this
	absolute	relative	Sensitivity coefficient	
Lamp irradiance (calibration)		0.30%	1	0.30%
Diffuser reflectance factor (calibration)		0.30%	1	0.30%
Lamp-diffuser distance (same as calibration distance for lamp)?	1 mm in 500 mm	0.20%	2	0.40%
Stability of lamp (short term)		0.10%	1	0.10%
Stability of lamp (drift/ageing)		0.10%	1	0.10%
Alignment of lamp				0.05%
Current stability of lamp (at 350 nm)	3 mA			0.29%
Diffuser stability (ageing)		0.10%	1	0.10%
Uniformity of diffuser		0.50%	1	0.50%

$$L_s = \frac{E_{\text{FEL}} \beta_{0-45}}{\pi} \frac{d_{\text{cal}}^2}{d_{\text{use}}^2} K_{\text{lamp\_stab}} K_{\text{align}} K_{\text{current}} K_{\text{diff\_stab}} K_{\text{unif}}$$

# Propagating the uncertainties

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# Combining and propagating uncertainties

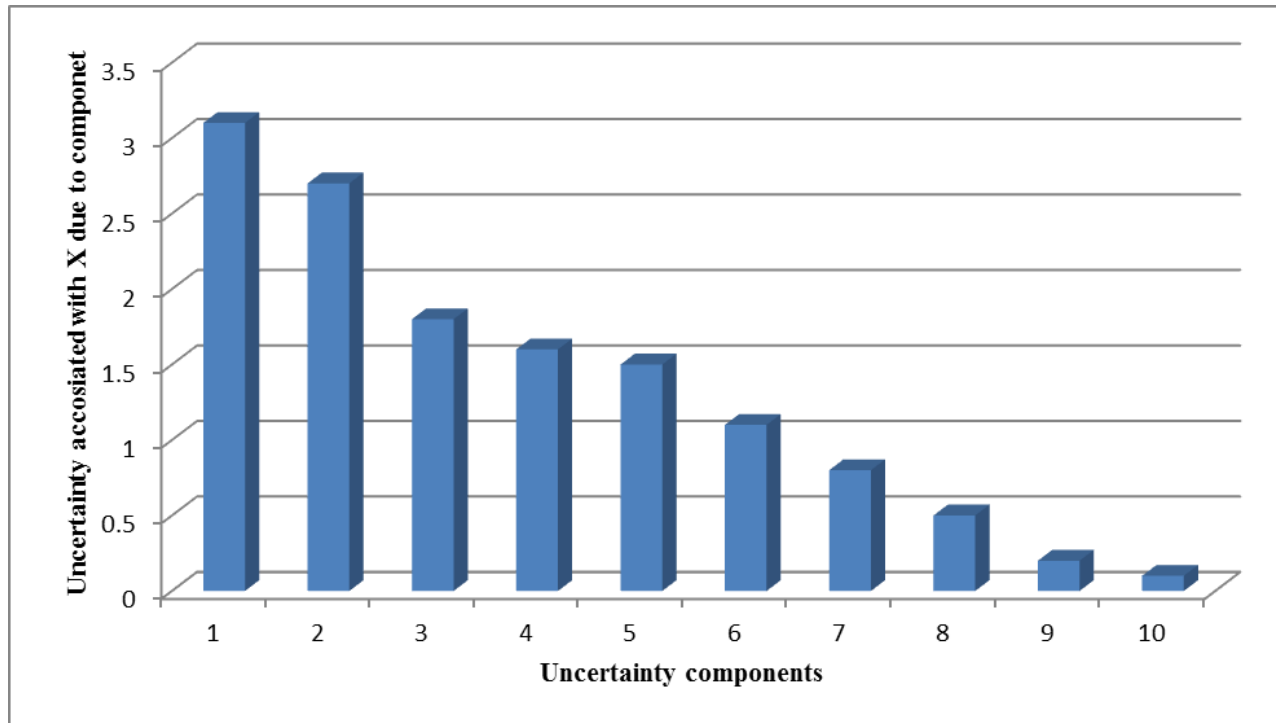
$$u_c^2(y) = \sum_{i=1}^n \left( \frac{\partial f}{\partial x_i} \right)^2 u^2(x_i) + 2 \sum_{i=1}^{n-1} \sum_{j=i+1}^n \frac{\partial f}{\partial x_i} \frac{\partial f}{\partial x_j} u(x_i, x_j)$$

Has a sensitivity coefficient  
Adding in quadrature (% or units)

This term is to do  
with correlation

Averages reduce by  $1/\sqrt{n}$

# Combining and propagating uncertainties

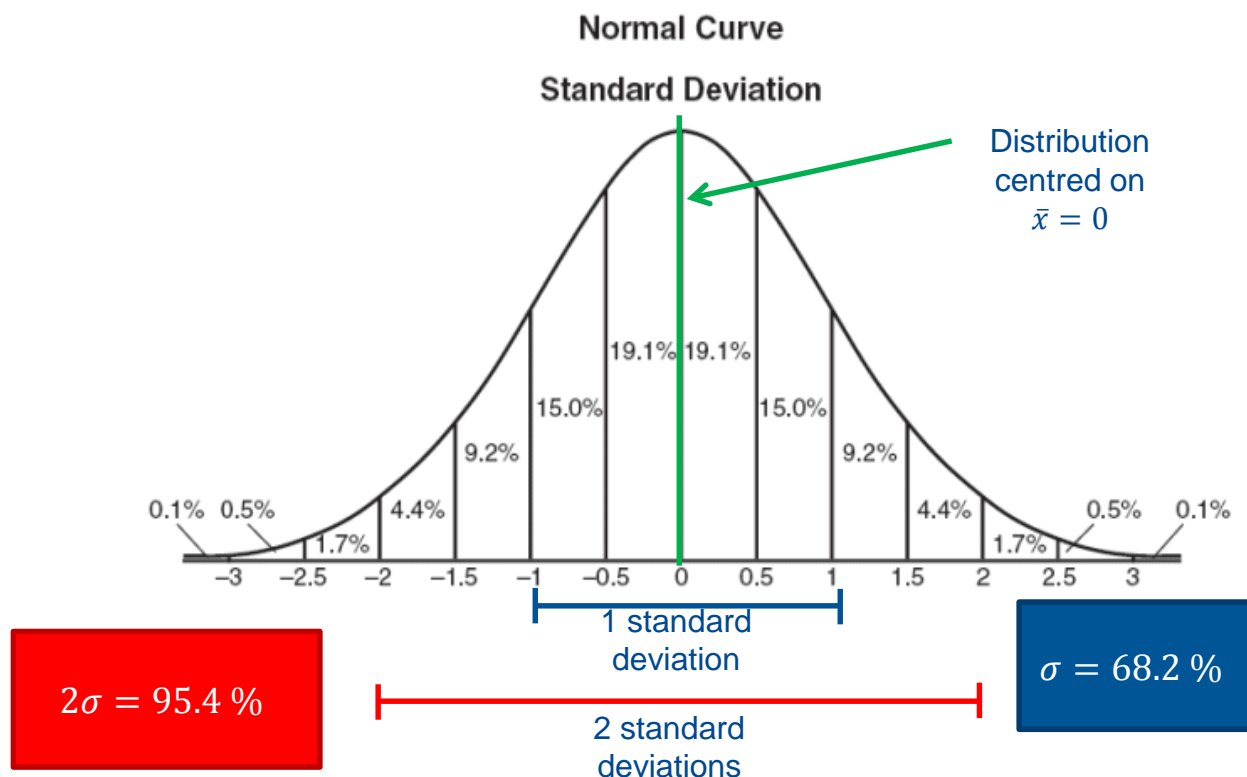


$$u(X) = 5.20\%$$

# Propagating the uncertainties

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# Expanding uncertainties



If the distribution is not Gaussian, then a different coverage factor is needed.

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